

ELECTRONICS INTRODUCTION

Designing a Next-Generation Surgical Robot Activity

Electronics Introduction

- ▣ Connect switch to receiver. Red connector goes in the last slot of receiver marked “B.”
 - Wires: red on the left; black on the right
- ▣ Connect servos to receivers. At this point, it does not matter which channel you plug each servo into.
 - Wires: white on the left; black on the right!!!!
- ▣ Make sure switch is turned off.

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- ▣ Connect switch to battery pack. Line up the black wire on the battery pack with the black wire on the switch.
- ▣ **Always turn ON transmitters first and then turn on switch.**
- ▣ Tare (zero) continuous rotation servos if they are rotating on their own (see next slide for instructions).
- ▣ **Always turn switch OFF first and then transmitters.**
- ▣ The switch should never be on when the transmitter is off!!!!
→ You will break the servos if you do this!

To Tare the Servos

- ▣ If the servo is rotating **fast**, then follow the procedure below **for coarse adjustment**:
 - Locate the hole with the internal screw .
 - ▣ It is next to where the wires come out of the servo.
 - Use a small Phillips head screwdriver to turn this screw until the servo stops moving or is moving very slowly.
 - If the servo spins faster when turning the screw, then turn it in the opposite direction until it stops or is moving very slowly.
- ▣ If the servo is rotating **slowly**, then follow the procedure below **for fine adjustment**:
 - Locate the servo adjustment switch on the transmitter that corresponds to the channel that your servo is plugged into (there is one for each channel).
 - Move this switch until the servo stops moving.

Electronics Tips

- ❑ Always make sure all switches are turned off when not in use; otherwise it drains the batteries.
- ❑ Receivers are very delicate so please handle with care
- ❑ Never use glue to attach any of the electronics (including the servos) to your device.
- ❑ Ensure that servos can be zeroed easily when attached to your device (internal screw should be exposed).
- ❑ Make sure batteries are easily accessible in case you need to check their voltage or replace them.
- ❑ Never glue anything on top of the accessory screw on the servos (so that devices can be completely disassembled at project end).