**Automatic Floor Cleaner Computer Program Packet**



Wikimedia Commons http://commons.wikimedia.org/

***Define the following terms***

Robot: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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Computer engineering: \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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***Construction***

Use the EV3 directions to build the “basic car” robot.

***Programming***

Use the LEGO software to create a program for each of the following tasks. Make sure each program has a clear title including your initials, such as*:* JQ SQUARE, JQ LINE, JQ CIRCLE.

1. Drive in a straight line for 2 feet.
2. Drive in a straight line for two feet, turn around and return.
3. Trace the square marked on the floor.
4. Follow the irregular line on the floor.
5. Drive in a smooth circle. (+10 bonus)

***Introduction***

You work as an engineering consultant for a major robotics and computer engineering company. Your newest job is to create the computer program to control the movements of their new assistive floor cleaner. Use the LEGO MINDSTORMS EV3 “basic car” robot to test and demonstrate your program.

***Client Statement***

Many people develop vision problems as they age. With diminished eyesight, a number of problems can arise, such as keeping one’s home clean. We have developed a small, self-contained floor cleaner. Our goal is to have the “robot cleaner” be able to move around the room in a random pattern, while using sensors to avoid running into furniture, pets and other obstacles in the room. This random pattern enables the robot to clean the entire floor if given enough time.

***Problem Statement*** (Define the problem in detail) \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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***Revised Problem Statement*** (Definition of the problem in detail including client modifications) \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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***Functions*** (what the product does)

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***Objectives*** (What the product is)

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***Constraints*** (The product must or must not)

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***Background Research***

As homework, use the internet to research robotics, computer programs, existing products that carry out similar functions, computer programs that control robot movements, robotic automation, and other related topics. Keep a record of relevant material and the source websites.

***Design Solutions*** (describe/sketch 3 possible design solutions)

Design #1 \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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Design #2 \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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Design #3 \_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_

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***Prototype Creation*** (Describe each part of the program in detail)

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***Test Design*** (How you will test your program design)

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***Test Results*** (describe the test results in detail)

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***Evaluation* of Results** (Based on the results; what worked, what did not work)

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***Future Recommendations*** (What you would recommend for future designs)

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