

Name:

Date:

Class:

# Horizontal Projectile Motion With Arduino Handout

## Learning objectives:

By the end of this project, you will be able to:

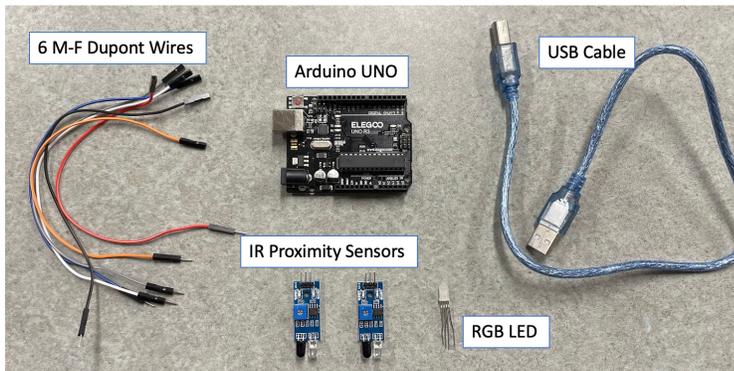
- Set up an Arduino speed sensor using IR proximity sensors.
- Understand the basics of Arduino programming.
- Determine the distance of a horizontally launched projectile given initial velocity and height.

## Materials:

- 1 Arduino UNO w/ USB cable
- 1 computer or laptop with Arduino IDE
- 2 IR proximity sensors
- 1 RGB LED
- 6 female-to-male Dupont wires
- 1 Arduino holder and ramp

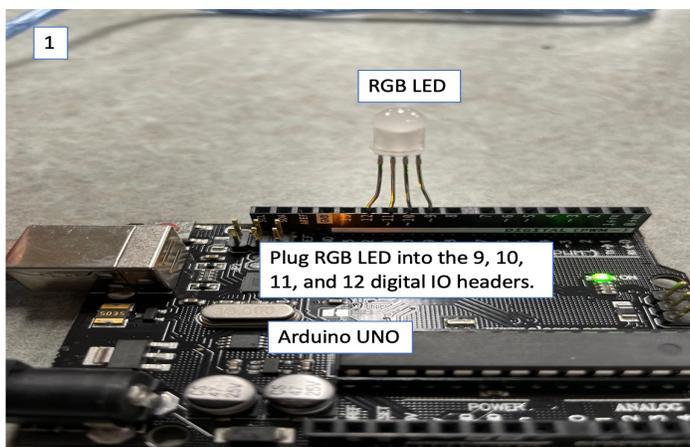
## Prepare:

1. Gather the following materials:



## Assemble

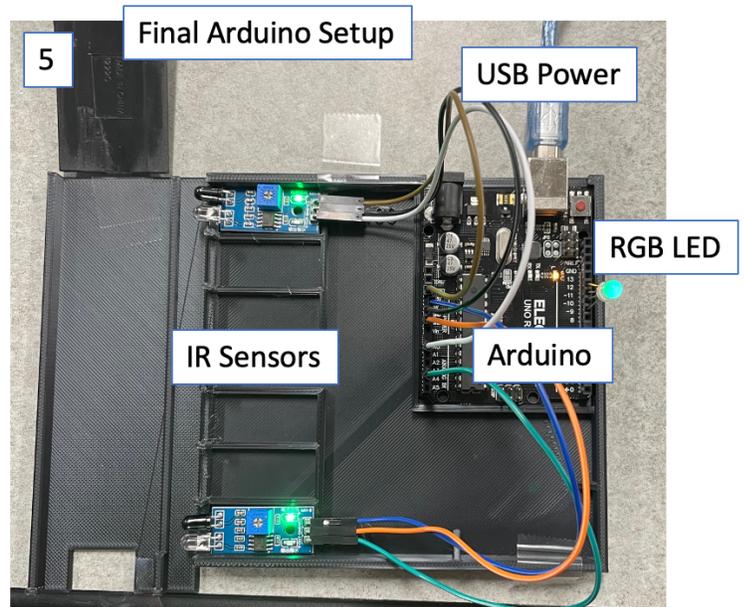
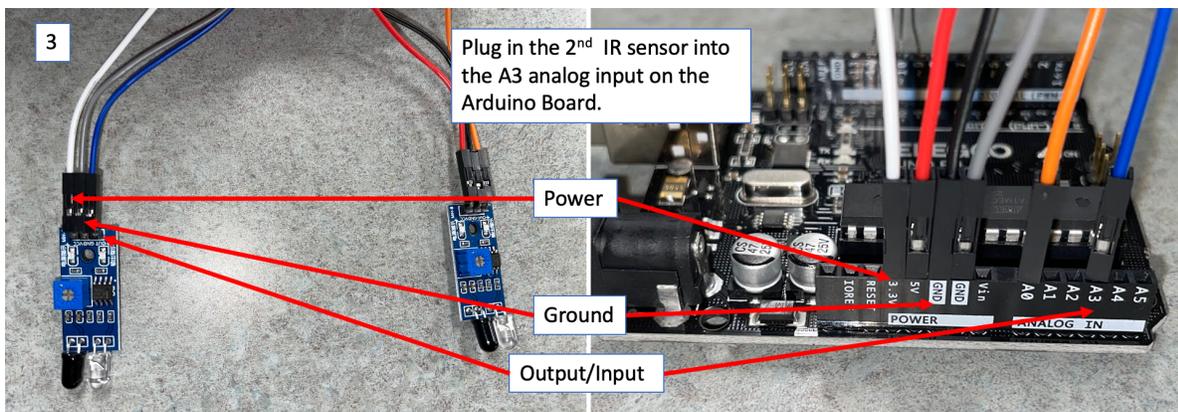
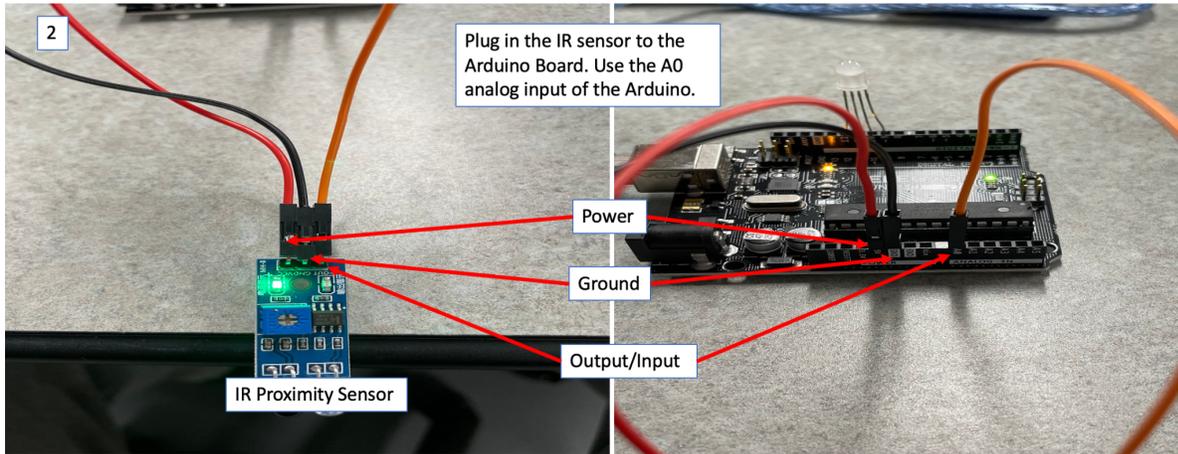
2. Follow the next five diagrams to set up your Arduino IR speed sensor.



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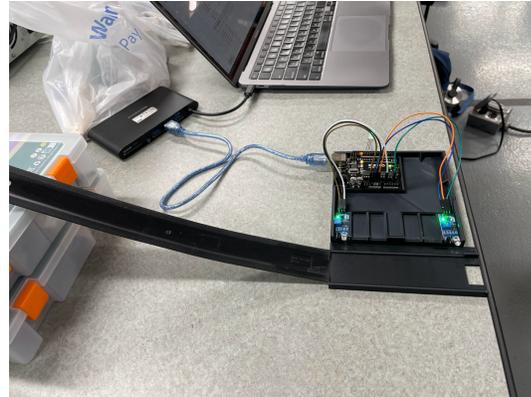
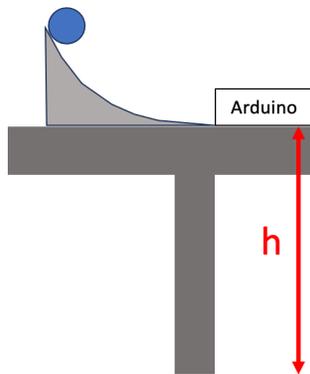
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5. Ramp setup:

- a. Place the Arduino speed detector at the edge of the table.
- b. Place the ramp just before the speed detector, as shown in the diagrams below:



What is the height of your launch point?

h = \_\_\_\_\_ meters

6. Test the ramp and Arduino setup.

a. Initial Velocity

- i. Place the projectile on the ramp and release it from the same spot three times. **DO NOT let the projectile hit the floor; catch it after it passes the speed sensor.**
- ii. Record these values in the table below:

	Trial 1	Trial 2	Trial 3	Avg (m/s)
Velocity				

b. Calculate Distance

- i. Use the following kinematic equation to determine the distance away the projectile will hit the ground. Use your calculated **Avg Velocity** and the **height** you measured.

$$d = v_i t + \frac{1}{2} a t^2$$

y-direction x-direction

