**Reflection Sheet**

1. How is your code similar to your brain's decision-making process?
2. What happens when you add new features (like sound)? How does this compare to how your brain processes multiple types of information?
3. How could you improve the robot's navigation to make it more "brain-like"?
4. What improvements would you make with more time?
5. How could this system be applied to real-world problems?
6. What engineering principles did you learn?

**Write a paragraph that addresses the previous questions for the challenge you completed. (7-10 sentences)**