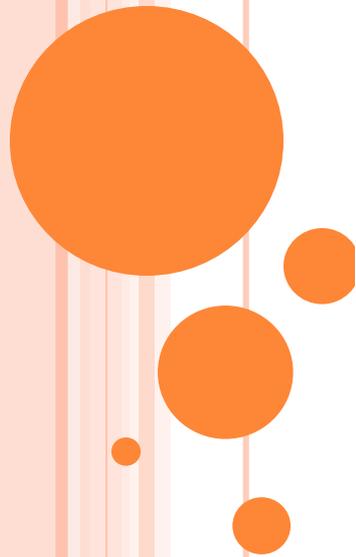


# What Is a Program?



# What Is a Program? Pre-Quiz

1. **What is a program?**
2. **What is an algorithm? Give an example.**

# What Is a Program? Pre-Quiz **Answers**

## 1. What is a program?

**A program is a sequence of instructions written to direct a computer to perform a task.**

## 2. What is an algorithm? Give an example.

**An algorithm is a clear and specific procedure for solving a problem in a finite number of steps.**

***Example:* The “addition algorithm” is a procedure for how to add any two numbers.**

# What is a program?

In today's world, **computers are everywhere!**

They are capable of running all sorts of programs to perform a huge variety of tasks. Just think about all the applications (apps) that are available for smart phones and tablets. They can do everything from playing chess to setting alarms to enhancing pictures.

Each app is a program designed to perform a specific task. As computers become even more widespread, the ability for people—like you—to be able to program becomes more and more important. **Programming is how you tell a computer how to perform a task that you want it to do.**

## Objective

In today's lesson, we:

- Investigate **programs** and **algorithms** — *What are they?*
- Become familiar with **simple commands** that are used in programs
- Learn how to use LEGO MINDSTORMS NXT **software** to write programs that the LEGO robot can **execute**

# What is a program?

- A **program** is a sequence of instructions written to direct a computer to perform a task.
- All computers can run programs.
- *Example*: A calculator is a computer that is programmed to perform arithmetic operations.
- Similarly, the LEGO MINDSTORMS NXT intelligent brick is a computer that we can program to perform different tasks, such as moving through a maze.

# What is an algorithm?

An **algorithm** is a clear and specific procedure for solving a problem in a finite number of steps.

**Example:**

***Addition algorithm:*** A systematic process that always produces the correct answer when numbers are to be added.

$$\begin{array}{r} 11 \\ 123 \\ + 789 \\ \hline 912 \end{array}$$

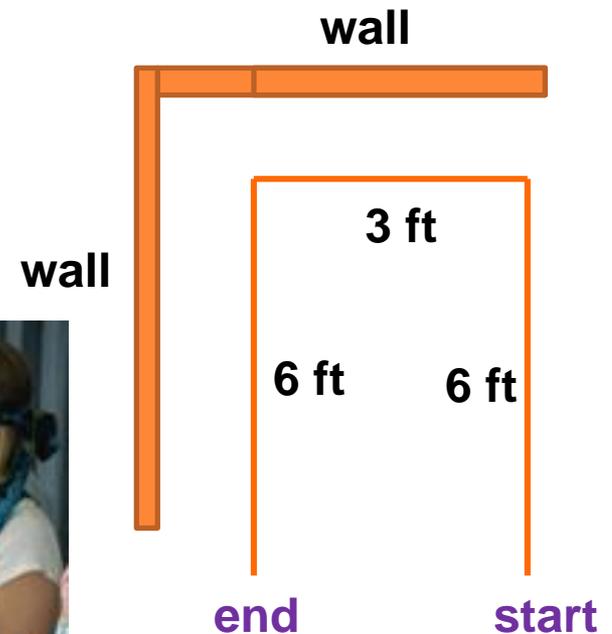
# What is Programming?

- **Programming** is designing an algorithm to solve a problem.
- You need to have commands that are clear and precise... the robot will follow them exactly, so each step is important.

# Mini-Activity: Programming as an Algorithm

(10 minutes)

- Using a roll of **tape**, make a short maze on the floor in the corner of the room resembling this diagram ↘
- **Blindfold** a volunteer “robot” and have him/her stand at the start of the maze, hands at his/her sides.
- Have another student—the “programmer”—give a series of commands (such as, go forward 2 steps, turn right, etc.) to instruct the volunteer to complete the maze.

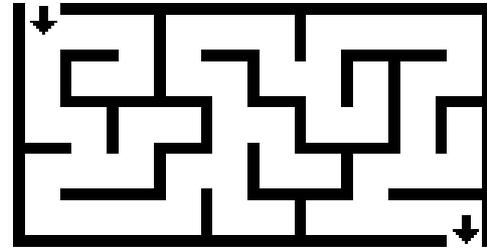


# Mini-Activity: Programming as an Algorithm

(continued)

## Observations and Questions:

- Did the “programmer” get the blindfolded “robot” through the maze?
- Did the “commander” always tell the “robot” to go the correct number of steps?
- Often, it is easier for the “programmer” to give instructions if s/he can tell the “robot” to go forward until s/he senses something. *Why?*
- This way, the “programmer” does not have to worry about telling the “robot” exactly how many steps to move forward.

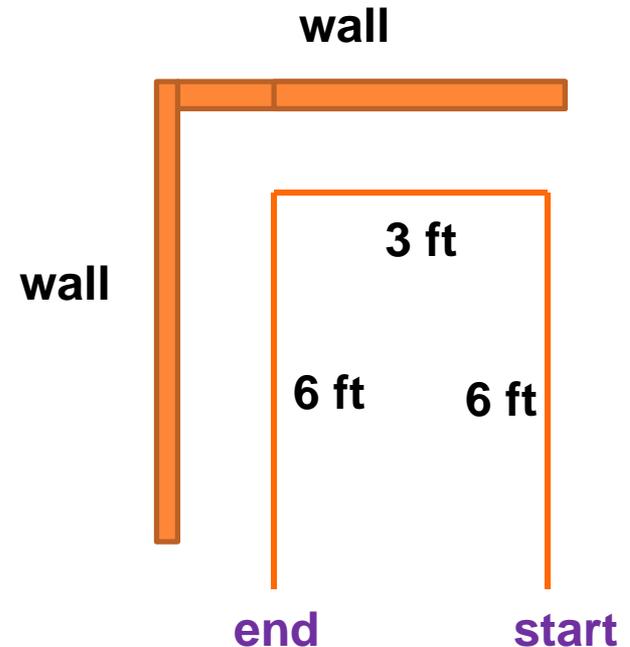


# Mini-Activity: Programming as an Algorithm (continued)

- Choose a new volunteer to be blindfolded.
- This time, permit the volunteer “robot” to stretch out his hands in front of his body to sense when he is approaching a wall.
- Have another student give commands to instruct the volunteer to get through the maze.



- Now, commands such as “go forward until you hit a wall” are permitted.



# Mini-Activity: Programming as an Algorithm (continued)

- Was it easier to give instructions the first time or second time?
- It is generally easier to tell a robot to go forward until it senses something (such as a wall) than to tell it exactly how far it should go before it turns.



# Mini-Activity: Programming as an Algorithm

(continued)

- **Note that the volunteer had to be told everything, that is, which direction s/he should move in, how long to move in that direction, how much to turn, etc.**
- **The LEGO NXT robot needs to be given exactly the same information. It knows nothing and is “blind” and will do exactly what you tell it to do. If you make an error in programming, the NXT won’t do what you want.**

# Quick Programming Using the NXT Brick

- We can program a robot to do some simple tasks just by using the LEGO NXT brick because the brick is a small computer.
- To turn on the brick, press the **orange button**
- Then use the arrows to scroll to the “NXT Program” screen and press the **orange button** twice more



# Quick Programming Using the NXT Brick (continued)

**Do This:** Let's program the robot to move forward for 5 seconds, then wait 2 seconds, turn right for 2 seconds, wait for 5 seconds, and then stop.



- Select the “**Forward 5**” block.



- Then use the gray buttons to scroll to the “**Wait 2**” block and select it with the **orange button**.



- Now scroll over to the “**Right 2**” block and select it.



- Scroll over to the “**Wait 5**” block and select it.

- Scroll over to the “**Stop**” block and select it.



- Press the **orange button** to run the program.

# Quick Programming Using the NXT Brick (continued)

## Do This:

- Press the gray button until you have cleared the 5 slots of the NXT Program.
- Select different blocks and **make your own quick programs** on the NXT brick.



# Quick Programming Using the NXT

## Drawbacks

Programming directly on the NXT brick is a **convenient** way to make simple programs and it is helpful to know the different features of the NXT brick.

However, this method of programming is not very efficient and won't work for everything we want to do, for the following the reasons:

- The NXT brick only provides a **small set of commands and durations** (timing choices) for programming.
- The NXT brick can only make programs that are a **maximum of 5 blocks long**.

# Quick Programming Using the NXT

## Drawbacks (continued)

It is not even possible to complete the maze you worked through in the activity by programming on the NXT brick.

So, from this point forward, we will use **LEGO MINSTORMS NXT software**.

This software enables us to:

- make longer programs
- use more sophisticated commands
- have control over the fine details of the program

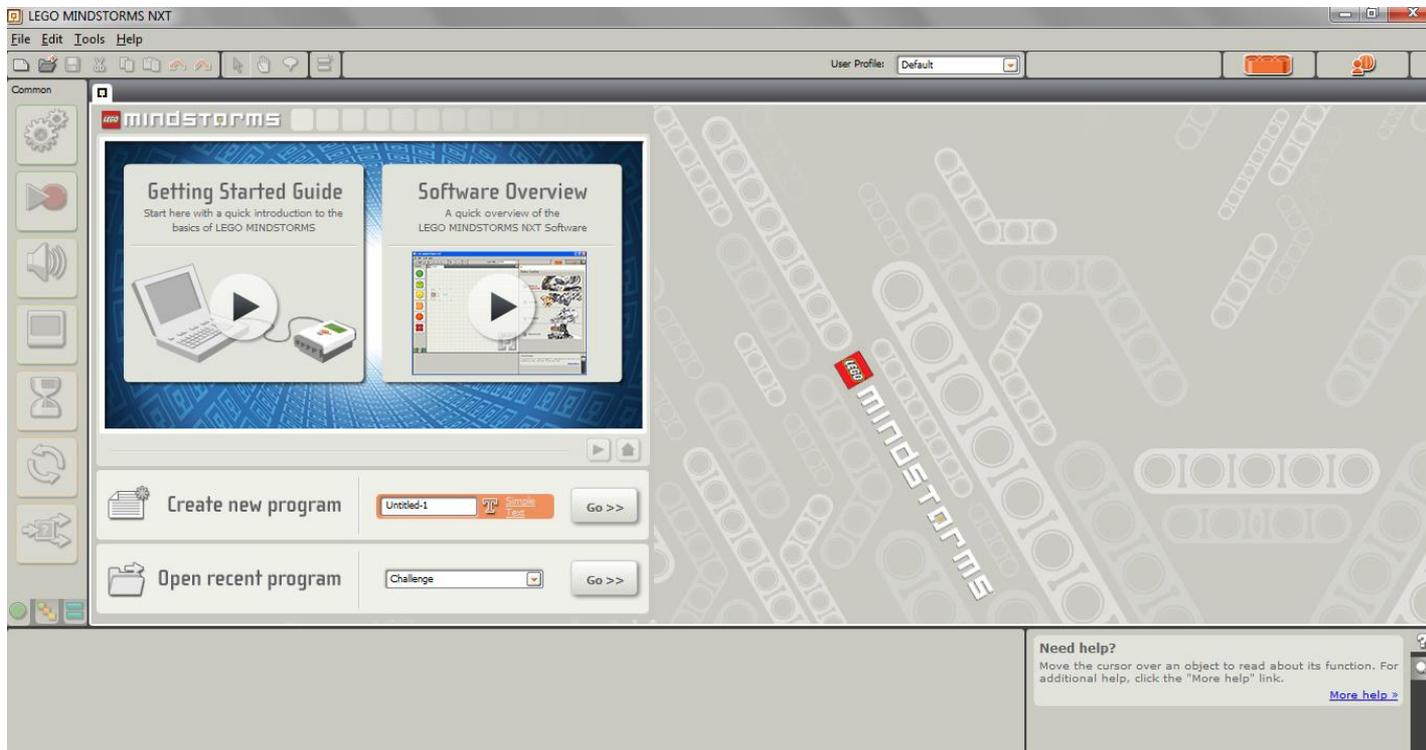
# DAY 2



# Getting Started with MINDSTORMS

Open the MINDSTORMS software by clicking on the **start menu** and selecting the “LEGO MINDSTORMS NXT” **icon**.

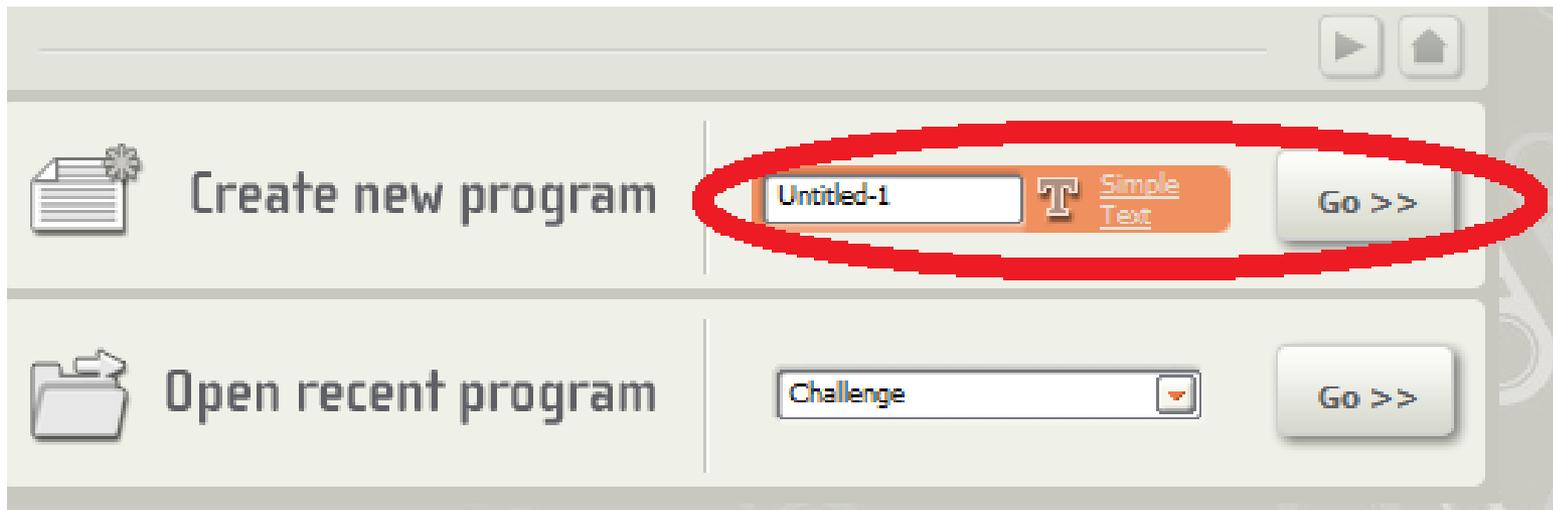
A window should open, looking like the one below. ↓



# Getting Started with MINDSTORMS (continued)

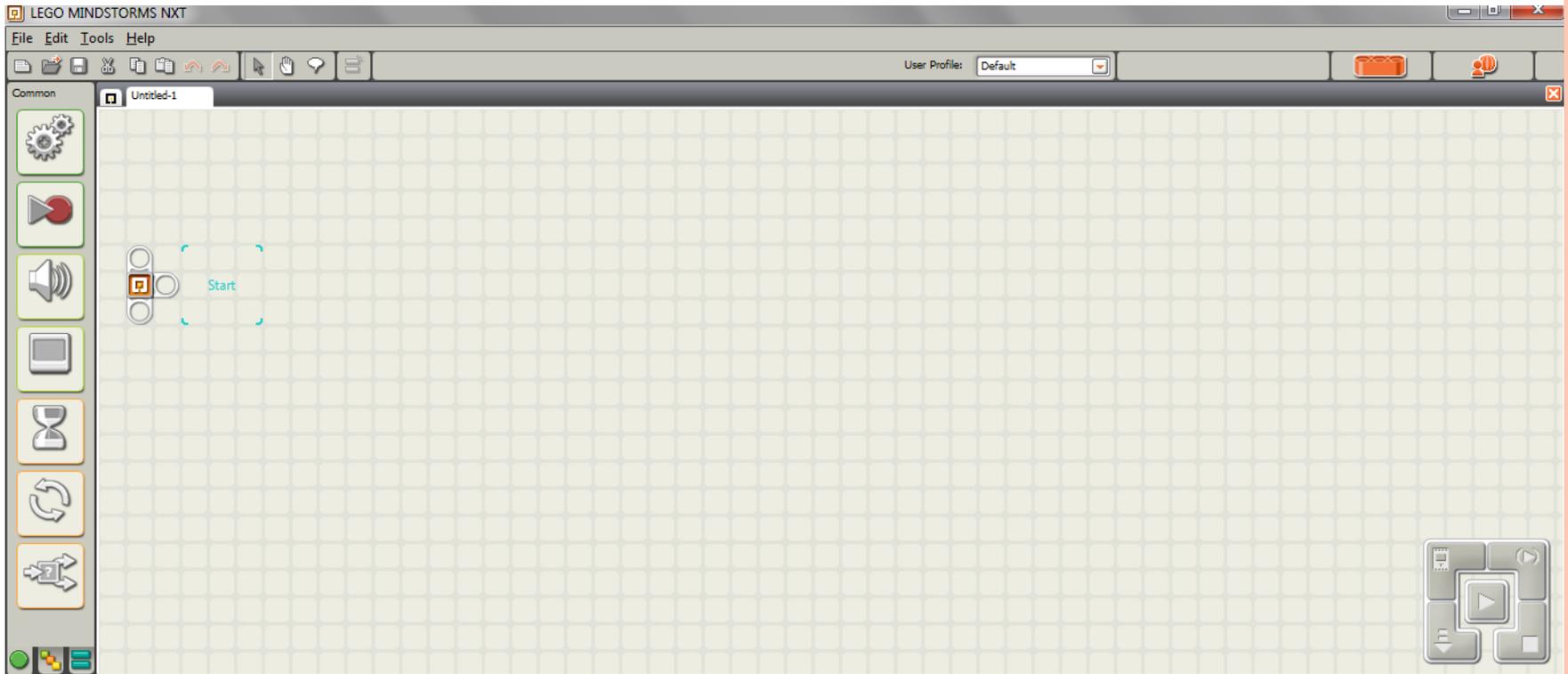
Move the cursor inside the dialogue box next to “**Create new program**” and type in a name for your program.

Then click “**Go >>**”

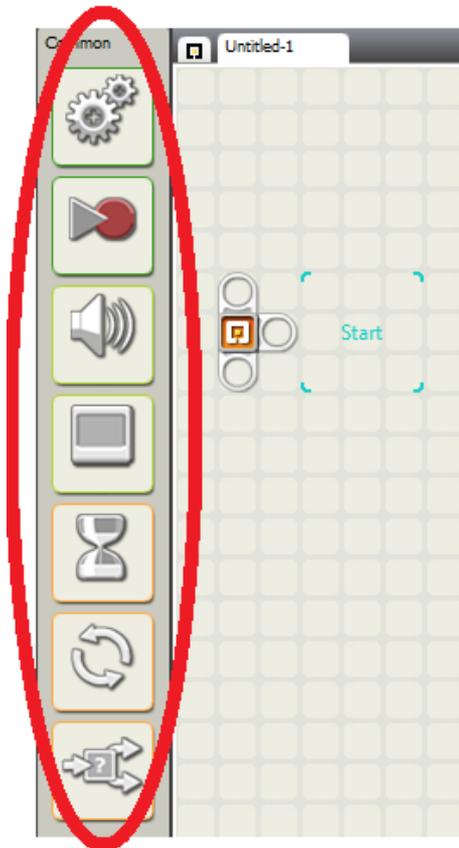


# Getting Started with MINDSTORMS (continued)

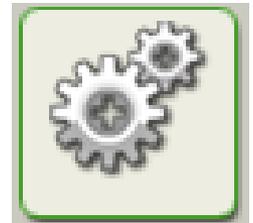
Your screen should now resemble the image below. ↓  
This is the **workspace** you will use to create your programs.



# Getting Started with MINDSTORMS (continued)



- The square icons on the left side of the screen represent different blocks that can be used for programming.
- In this lesson, we will be using only the **move block**, which looks like this:

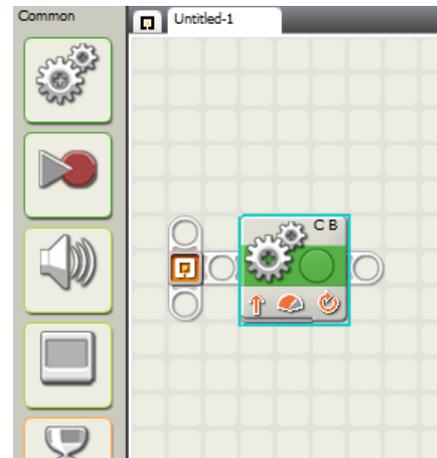


# The Move Block

- Move your cursor over the move block icon.
- Click and drag the move block into the blue “start square”



- When you are done, the top left quarter of your screen should resemble the image shown to the right →



# The Move Block (continued)

- The move block in your program should be highlighted in a thin light blue outline. If it is not, highlight the block by clicking on it.
- Whenever you highlight a block, the bottom of the screen gives you details about that block.
- The bottom of your screen should resemble the image below. ↓



# The Move Block: Port



- A move block is used to control one or more motors.
- Next to “Port:” notice the checkmarks next to “B” and “C.” This means that this block is set to control the motors attached to ports B and C of the NXT.
- This is good for us, because the motors of the taskbot we built should already be connected to ports B and C.
- You will rarely need to change the “Port” settings.

# The Move Block: Direction



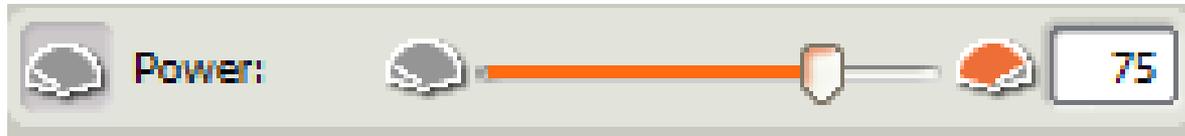
- “**Direction**” controls which way the motors are set to rotate.
- The upward arrow (currently selected) means **forwards**, but we also have the options of selecting **backwards** (the down arrow) or **stop** (the stop sign).

# The Move Block: Steering



- **Steering** allows us to easily make the robot turn.
  - Dragging the pointer to the left makes the robot **turn left**
  - Dragging it to the right makes the robot **turn right**
  - The farther to one side the pointer is dragged, the **sharper the turn** will be
  - If the pointer is dragged all the way to one side, the robot should **turn in place**

# The Move Block: Power

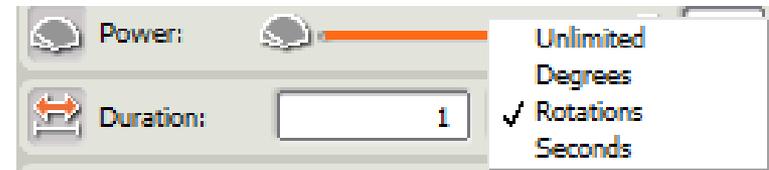


- The Power setting controls **how fast the motors turn.**
- Increasing or decreasing the power too much tends to decrease the consistency of the motor movement, so it is recommended that “75” is used, unless there is a good reason to change it.

# The Move Block: Duration



- **Duration** controls **how long the motors rotate**.
- Clicking the dropdown arrow, reveals several options. ↓
- We will talk about when/how to use **“Unlimited”** in the next lesson; it will **NOT** make the robot go forever if used on its own.
- **“Degrees”** allows you to control precisely how many degrees the motor spins, where  $360^\circ$  is one rotation of the motor.
- **“Rotations”** allows you to control how many times the motor spins. (1 rotation = 1 full spin)

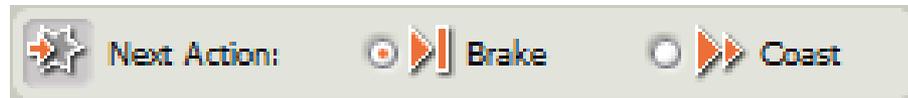


# The Move Block: Duration (continued)



- **“Seconds”** allows you to control the length of time the motors turn for.
- **Rotations is generally preferred over Degrees/Seconds because:**
  - We generally need to make the robot move a few rotations in a direction and 3 rotations is much less tedious to type than  $3 \times 360$  degrees = 1080 degrees.
  - Depending on factors such as the power setting and the amount of battery charge, the motors can spin different amounts of time in a second. But a motor spinning 1 rotation should always spin exactly the same amount.

# The Move Block: Next Action



- You will almost never need to use the Next Action option
- It simply controls whether the motors are locked after performing a command or not
- This option matters if the robot is on a steep incline.
  - “Brake” prevents the robot from rolling back down after it executes a command
  - “Coast” allows the motors to be turned by gravity

# Move Block: Helpful Hints

The robots are not perfectly consistent or alike but generally:

- For every **1 rotation forward**, the robot moves **about 7 inches**.



- Pulling the steering pointer all the way in one direction and setting duration to “.5 rotations” produces **a turn that is close to 90°**

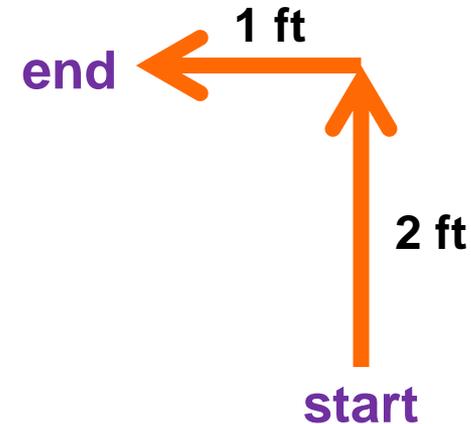


# Example Program

**Program the robot to follow the track shown below. ↓**

**Start by breaking this track down into steps:**

- 1. Move forward for 2 feet**
- 2. Turn left**
- 3. Move forward for 1 foot**

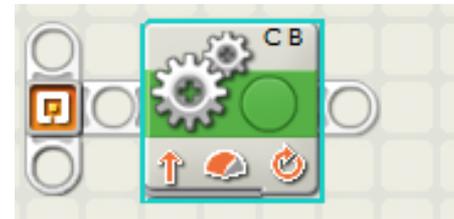


# Part 1: Move forward for 2 feet

- First, we drag a **move block** into the program.
- Now we know we are moving straight forward. So this means, that we want to keep the **upwards arrow** selected.
- Next, we have to decide what to do about the **steering**. Since the robot is moving straight forward, we do not want the robot to turn at all, so we do not need to change the steering.
- Finally, we need to determine the **duration**:  
In Helpful Hints, we learned that 1 rotation is about 7 inches  
1 ft = 12 inches, so 2 ft = 24 inches  
24 inches divided by 7 inches  $\approx$  3.5  
So to go 2 ft, we need to go about 3.5 rotations

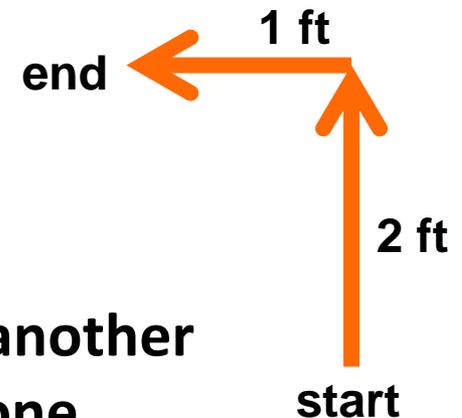
# Part 1: Move Forward for 2 feet (continued)

So far, the program should look like this: ↓

A screenshot of the 'Move' block configuration interface in the LEGO Mindstorms software. The block is titled 'Move' and has a gear icon with an 'R' label. The configuration is as follows:

- Port:** A, B, and C are selected with checkboxes.
- Direction:** Forward (up arrow) is selected with a radio button.
- Steering:** Motor C is selected for the left side and Motor B for the right side. A steering slider is positioned in the center.
- Power:** A slider is set to 75.
- Duration:** A text field contains '3.9' and a dropdown menu is set to 'Rotations'.
- Next Action:** 'Brake' is selected with a radio button.

# Part 2: Turn Left

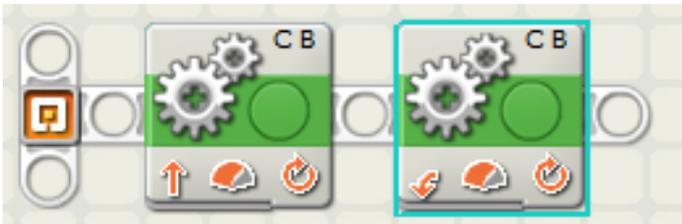


- We want the robot to **turn left** next, so drag another move block down and set it next to the first one.
- Since the turn forms a rectangular corner, it is a **90° turn**.
- Recall from “helpful hints” that we said moving the steering pointer all the way to one direction for a duration of .5 rotations gets us close to a 90° turn.
- So keeping the direction forward (the robot is moving forward as it turns), pull the steering pointer all the way to the left, and set duration to 0.5 rotations.

# Part 2: Turn Left (continued)

So far, the program should look like this.

The second move block is highlighted, and the details are shown below. ↓



**Move**

Port:  A  B  C

Direction:  ↑  ↓  ←

Steering:

Power:  75

Duration:  Rotations

Next Action:  Brake  Coast

0 A  
0 B  
0 C

R

# Part 3: Move Forward for 1 Foot

- Just as in Part 1, the robot is moving straight forward, so we do not need to change **direction** or **steering**.
- We do need to figure out the **duration** again.  
This time, the robot should move 1 foot, or 12 inches forward.  
Remember 1 rotation is about 7 inches.  
So 12 inches divided by 7 inches  $\approx 1.75$   
So let's set the duration to 1.75 rotations

# Part 3: Move Forward for 1 Foot (continued)

The **complete program** should look like this, with the details of the highlighted third block shown below. ↓



**Move**

Port:  A  B  C

Direction:  ↑  ↓  ↻

Steering:  C  B  A

Power: 75

Duration: 1.75 Rotations

Next Action:  Brake  Coast

# Downloading the Program onto the NXT

Now it's time to download the program onto your NXT:

## Do This:

- **Plug** one end of the USB connecting cable into the computer, the other into the NXT
- Make sure both ends are fully inserted
- Turn on the NXT by pressing the **orange button**
- Look for this set of buttons in the bottom right corner of your computer screen →
- To download the program, click on the **down arrow**
- Then press the **orange button** until the program starts running



# What Is a Program? Post-Quiz

1. **What is a program?**
2. **What is an algorithm? Give an example.**

# What Is a Program? Post-Quiz **Answers**

## 1. **What is a program?**

**A program is a sequence of instructions written to direct a computer to perform a task.**

## 2. **What is an algorithm? Give an example.**

**An algorithm is a clear and specific procedure for solving a problem in a finite number of steps.**

***Example:* The “addition algorithm” is a procedure for how to add any two numbers.**

# Vocabulary

**program:** A sequence of instructions written to direct a computer to perform a task.

**algorithm:** A clear and specific procedure for solving a problem in a finite number of steps.

# Images Sources

Slide 1: Girl looking at laptop monitor; source: Microsoft® clipart: <http://office.microsoft.com/en-us/images/results.aspx?qu=computer&ex=1#ai:MP900430487> |

Slide 8: Girl blindfolded in trust game; source: 2005 Tracee L. Jackson, U.S. Marine Corps via Wikimedia Commons: <http://commons.wikimedia.org/wiki/File:Blindfoldlowres.gif>

Slides 10, 11: Blindfolded kids in trees; source: North Carolina State Parks: [http://www.ncparks.gov/Visit/parks/hari/pics/harp\\_maze.jpg](http://www.ncparks.gov/Visit/parks/hari/pics/harp_maze.jpg)

Slide 9: Maze line drawing; source: 2005 ZeroOne, Wikimedia Commons: <http://commons.wikimedia.org/wiki/File:Maze01-01.png>

Slide 15, 39: Girl on floor with laptop and hands raised; <http://office.microsoft.com/en-us/images/results.aspx?qu=computer&ex=1#ai:MP900448599> |

Slide 18: men's feet stepping; source: Microsoft® clipart: <http://office.microsoft.com/en-us/images/results.aspx?qu=feet&ex=1#ai:MP900425511> |

Device and programming images from LEGO MINDSTORM NXT User's Guide <http://goo.gl/wuhSUA>

Screen captures and diagrams by author