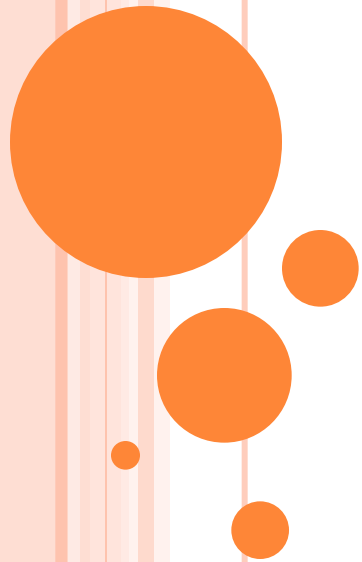


# Human and Robot Sensors



# Human and Robot Sensors Quiz

1. **How many sensors or senses do humans have? List them.**
2. **Describe how any two of those human “sensors” work.**
3. **Give at least three examples of robot sensors that are similar to human senses.**

# Human and Robot Sensors Quiz

1. **How many sensors or senses do humans have? List them.**

Humans have 5 main senses: vision, hearing, smell, touch and taste. Our sensors include the eyes, ears, nose, skin and tongue.

Additional sensors include temperature sensors, body position sensors, balance sensors and blood acidity sensors.

2. **Describe how any two of those human “sensors” work.**

**Eyes:** Take in the surrounding light and relay it to nerve cells that send images to the brain.

**Ears:** Take in sound waves from the air and vibrate, sending vibrations through the inner ear to hair cells that send signals through the nerves to the brain.

**Nose:** Particles are inhaled into the nose and nerve cells contact the particles and send signals to the brain.

**Skin:** Sensors all over the skin are activated and send signals to the brain through the nervous system.

**Tongue:** Taste buds are made of small cells that have little hairs that are activated by particles in food. The hairs send signals through nerves to the brain.

3. **Give at least three examples of robot sensors that are similar to human senses.**

Light and ultrasonic sensors are like eyes (vision). Sound sensors are like ears (hearing). Touch, temperature and pressure sensors are like skin (touch).

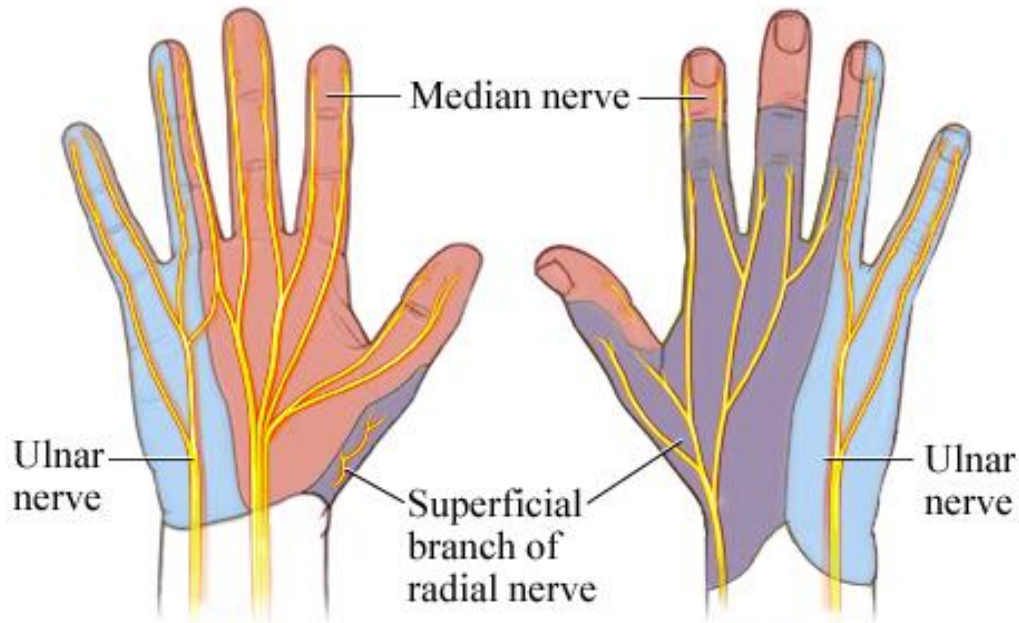
# Lesson Objectives

The following slides include:

1. **A rigorous background in human sensors and their engineering equivalents.**
2. **A review of human sensors, followed by robot sensors, to set the context for the hands-on activities involving sound sensors on the LEGO MINDSTORMS NXT robot.**
3. **How the robot takes sensor input, and uses it to make decisions to cause movements.**

# What is a Sensor?

A sensor is a device that measures a physical quantity



Touch example:

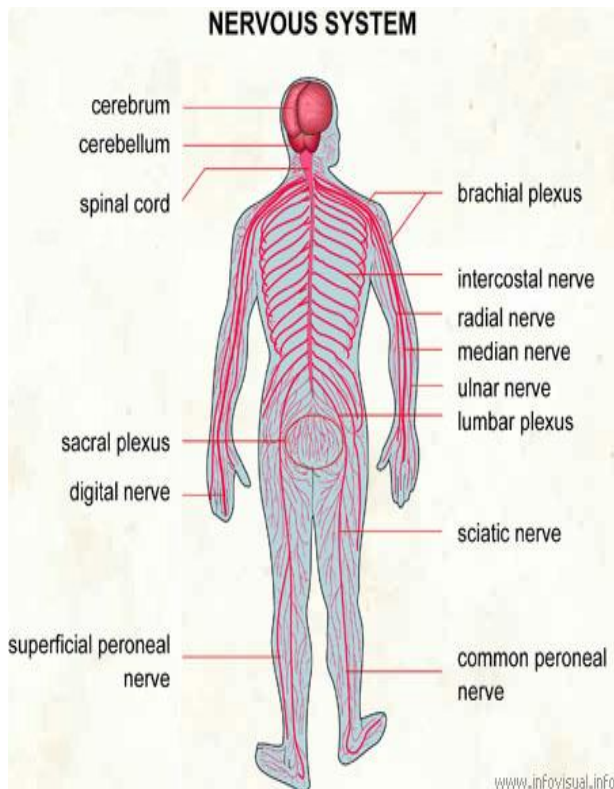
- The skin in your fingers contains millions of sensitive nerve endings that can detect stimuli, such as temperature.
- When you touch an object, sensors on your fingers send signals to your brain so that it recognizes it as being hot or cold.
- This stimulus is converted to neuronal impulses that are sent via nerves to a specific region in the brain that interprets it as being hot or cold.
- The same process happens with stimuli such as pressure and pain signals.

# Human Sensors

- ▶ Your **sensory organs** (eyes, ears, nose, tongue and skin) provide information to your brain so that it can make decisions. This is very similar to the working of robot sensors. Your brain continuously uses the information that it receives from your sensory organs to make your body work correctly.
- ▶ Humans have 5 major senses:
  - Your **eyes** enable you to see the world
  - Your **ears** enable you to hear sounds
  - Your **nose** lets you smell the many scents in our world
  - Your **tongue** lets you taste
  - Your **skin** lets you feel objects through touch
- ▶ Plus several additional sensors in the body that you do not notice directly:
  - Sensors in the inner ear give the brain information about balance
  - Sensors in our muscles inform the brain of our body positions
  - Sensors throughout your body that sense temperature
  - ....and others

# Human Sensors – Signal Transmission

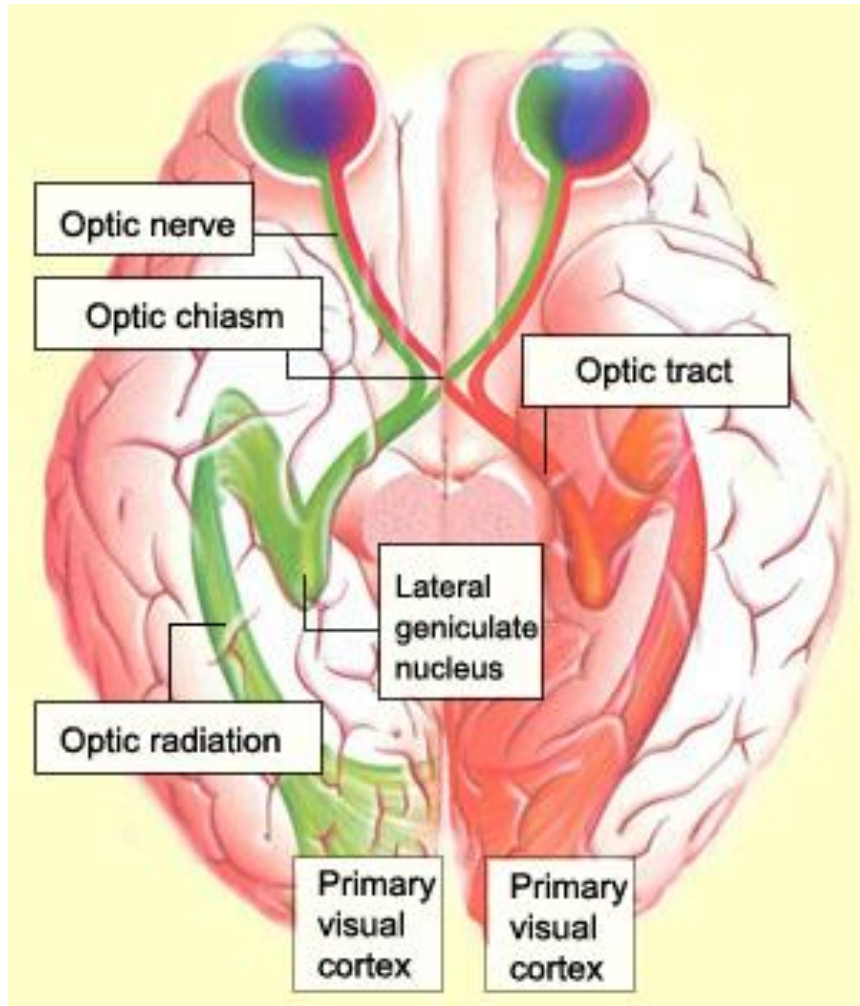
When the sensors of the human body detect a stimulus, they send this information through the nervous system (similar to wires) to the brain.



The human nervous system has two main parts:

1. The **peripheral nervous system** is a series of branches of single nerves. These nerves connect to every sensor in your body. They send signals to other nerves, which send signals to more nerves until the signal reaches the second part of the nervous system: the central nervous system.
2. The **central nervous system consists** of your spinal cord and your brain. The spinal cord is composed of bundles of nerves that are surrounded by bones for protection. Once a signal from a sensor reaches the spinal cord, it is sent up the cord to the brain. The brain decides what to do based on the information received.

# Vision: How Does the Brain Know What We Look At?

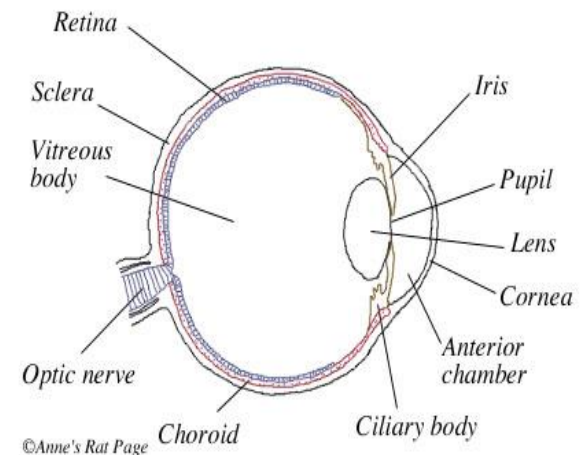


- Light (stimulus) enters the eye.
- It passes through the optic nerve.
- Lateral geniculate nucleus (LGN) relays the information to the visual cortex.
- Visual cortex processes this information.



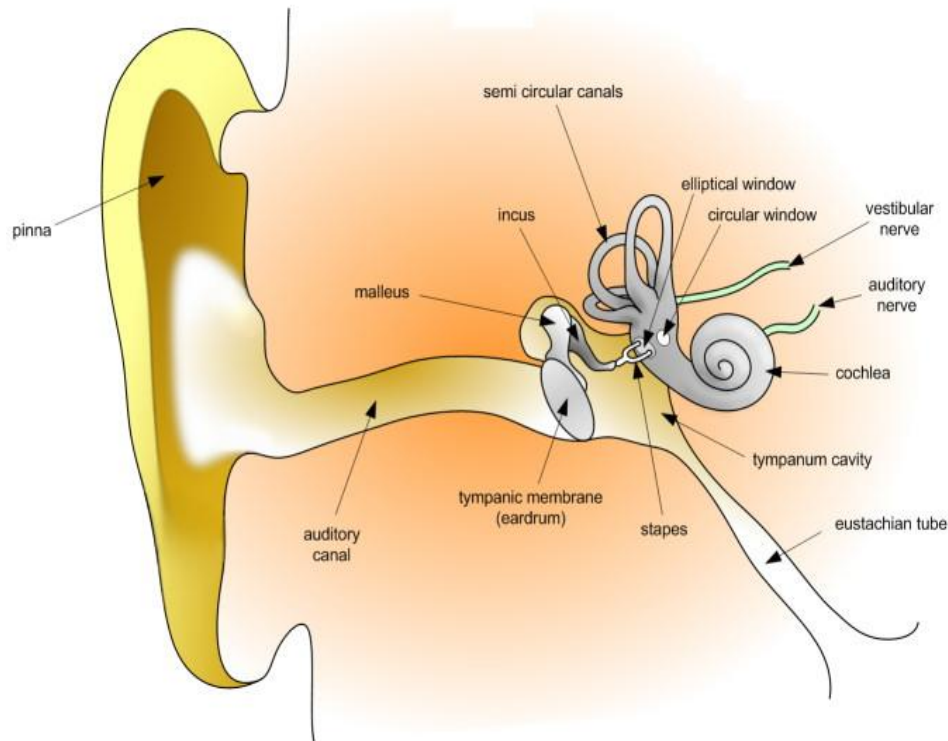
# How Do Your Eyes Work?

- ▶ First, light enters your eye, and is **refracted**, or bent, by the **cornea**, the outermost part of your eye.
- ▶ Refracted light is directed right at the **pupil**, a small hole in the center of the **iris**, the colored part of the eye. The iris can change the pupil size to control how much light enters.
- ▶ Light that goes through the pupil is redirected by the eye's **lens**, which points the light at nerve cells in the back of your eye.
- ▶ The back of the eye has two types of nerve cells:
  - ▶ **Cones** detect colors and fine details in good light. They are concentrated in the center of the back part of your eye.
  - ▶ **Rods** detect the presence of objects in bad light and are concentrated on the sides of the back part of your eye.
- ▶ Cones and rods send signals through the **optic nerve** to the brain.



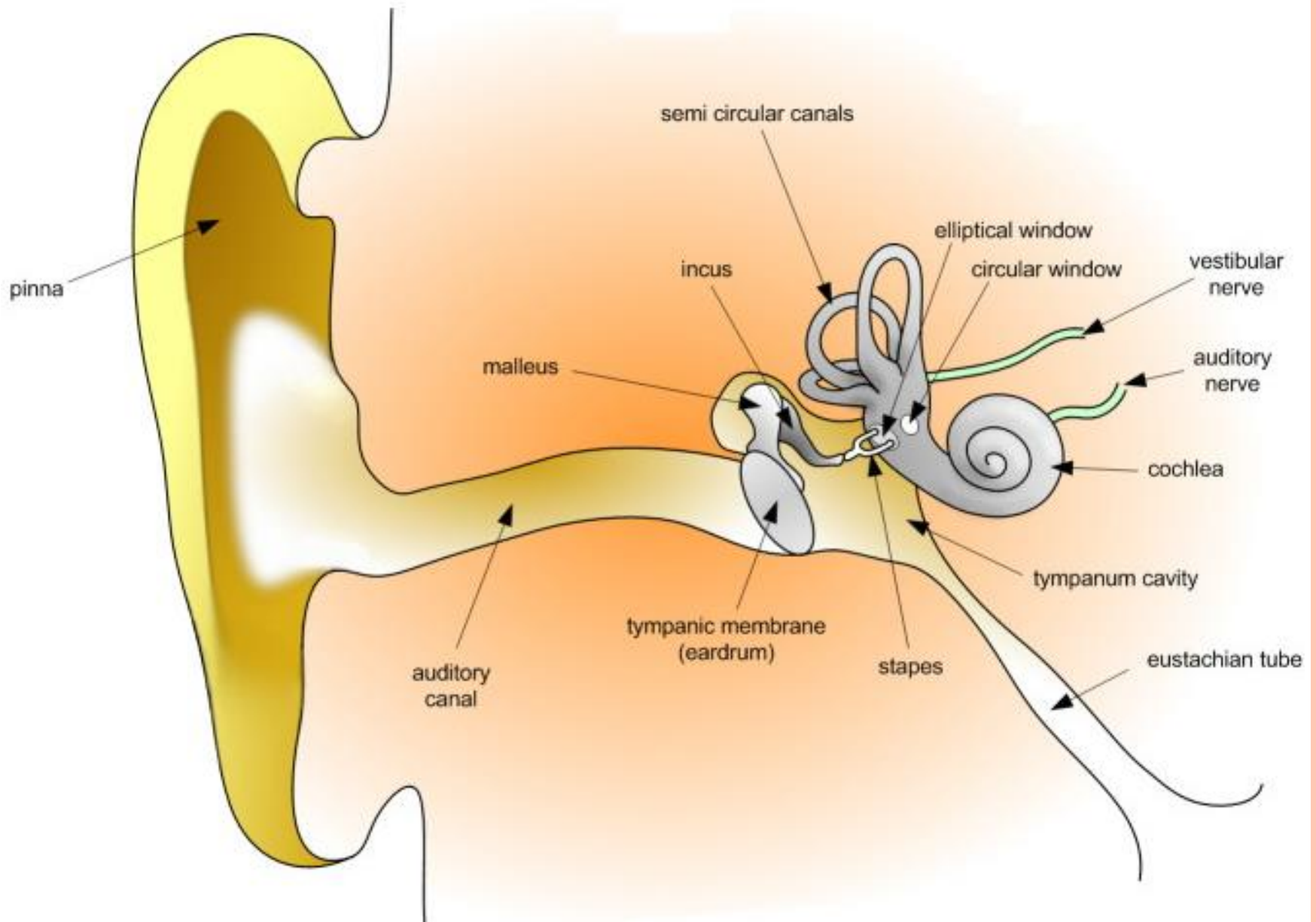
# Sound: How Do Your Ears Work?

- Sound waves enter the **ear canal** and cause the *eardrum* to vibrate.
- Eardrum vibrations are carried through the **hammer, anvil,** and **stirrup** of the ear to a fluid-filled structure called the **cochlea**.



- Different pitches cause different parts of the fluid in the cochlea to vibrate.
- When cochlear fluid vibrates, it moves hairs connected to nerve cells, which send signals to the brain through the **auditory nerve**.
- The brain helps you recognize the sound.

# Parts of the Human Ear

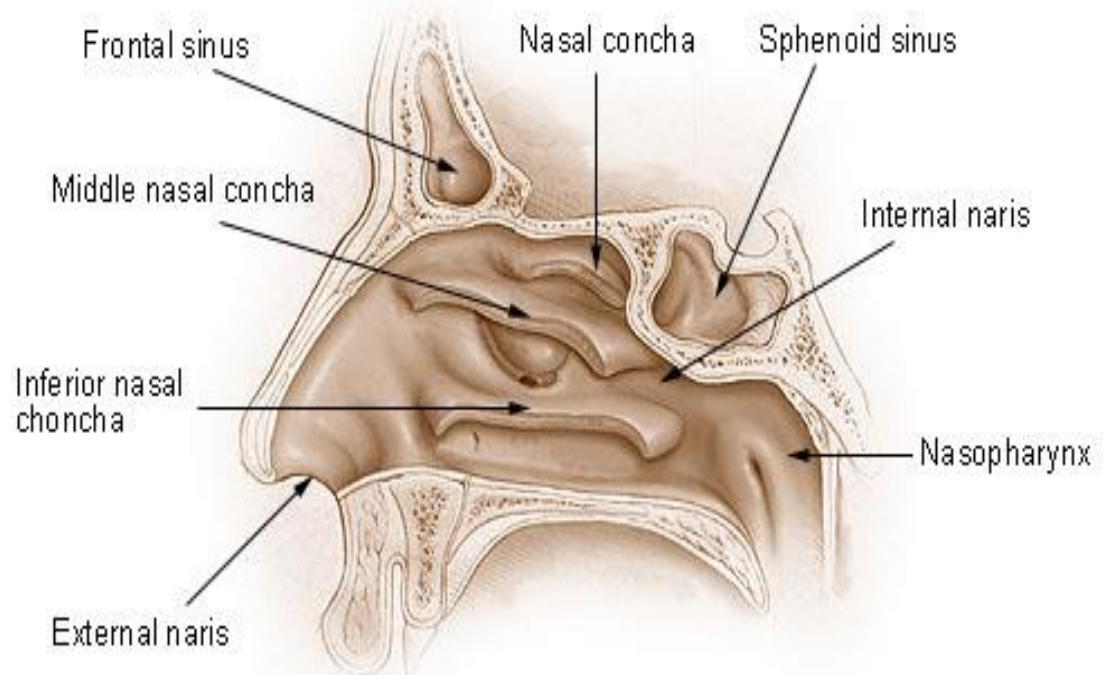


# Smell: How Do We Smell Using Our Noses?

- ▶ Small particles of almost everything around us can be found in the air.
- ▶ These particles enter the nose when you breathe in and contact nerve endings in the upper nasal passage.
- ▶ These nerve endings send signals through the nervous system to the brain, which makes sense of the smell.
- ▶ Humans can distinguish between hundreds of different smells. Dogs can distinguish between thousands.



**Nose and Nasal Cavities**

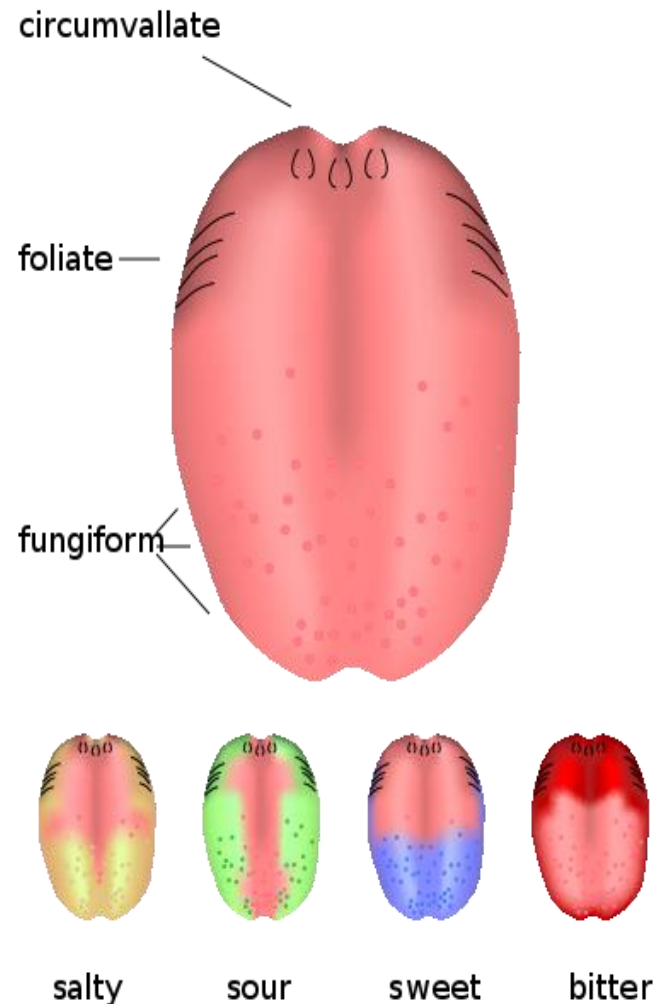


# Taste: How Do We Taste Using Our Tongues?

- The tongue has sensory receptors called **taste buds** that can detect one of 5 different flavors: **sweet, salty, bitter, sour, umami**

Umami is a flavor in many high-protein foods, such as meats, as well as cheeses, tomatoes and mushrooms, and is generally described as being a savory, meaty taste.

- ▶ Taste buds are comprised of cells called **gustatory receptor cells**, which have tiny hairs that detect taste from the food that you eat. The hairs send information to the cells, which send signals through the nervous system to the brain, which interprets the information as taste.
- ▶ What is the difference between **taste** and **flavor**?  
Flavor includes taste, but also a little more. It comprises taste, smell, texture of food, and even other sensations such as pain when you eat something spicy. Eating food with your nose blocked shows a marked decrease in flavor, even though the taste is the same.





# Robot Sensors



## ○ What do robot sensors do?

- Gather information from the surroundings and send it to the computer brick.
- Robot sensors can only be used if the robot's program asks for information from them!
- Similarly, the robot can only act on information from the sensors if its program tells it to do so!

## ○ How do sensors send signals to the computer brick?

- The sensors send information through the wires (similar to the nervous system in the human body) that connect them to the computer brick, which uses the information if its program requires it.

# How Do Robot Sensors Work?

## Touch Sensor

- A touch sensor is a button-like protrusion.
- When bumped, it sends a signal to the computer brick saying that it has been touched.



touch sensor

## Light Sensor (works in two different ways)

- Detects the amount of ambient light and converts it to a numerical value that is sent to the computer brick.
- Determines the brightness of an object by sending out light and detecting how much is reflected back. It converts the amount of reflected light to a numerical value and sends it to the computer brick. If no object is in front of the sensor, it sends a value of zero.



light sensor

# How Do Robot Sensors Work?

## What is sound?

- Sound is made of *sound waves* or vibrations in the air.
- Louder sounds produce larger vibrations.
- Higher pitch sounds produce more frequent vibrations.

## Sound Sensor

- In a sound sensor, a thin piece of material called a *diaphragm* vibrates when hit by sound waves (similar to a human eardrum).
- If the diaphragm vibrations are large enough to be detected, the sound sensor sends a signal to the computer brick saying that it has heard a sound.



sound sensor



# How Do Robot Sensors Work?

**Ultrasonic Sensors have two parts:**

- A **transmitter** sends out a signal that humans cannot hear.
- A **receiver** receives the signal after it has bounced off nearby objects.

**The sensor sends out a signal and determines how long the signal takes to come back:**

- If the object is very close to the sensor, the signal comes back quickly.
- If the object is far away from the sensor, the signal takes longer to come back.
- If objects are too far away, the signal takes so long to come back (or is so weak when it comes back) that the receiver cannot detect it.

**The ultrasonic sensor sends a message back to the computer brick, telling it the time taken for the signal to return. The computer brick uses this data to compute its distance to the object.**



ultrasonic sensor

Can you name a similar process performed by animals?

# What Are Robot Equivalents of Human Sensors?

Human Sensor	Equivalent Robot Sensor
eyes	light sensor, ultrasonic sensor
ears	sound sensor
skin	touch, temperature, pressure sensors
nose	none yet...
tongue	none yet...

# Real-World Examples Abound

- Researchers study how pressure sensors in the human fingers and the multiple fingers work to help them design efficient robotic hands.



- Touch sensors used in smart phones and tablets!
- Study of how the human eye works helps in the design of cameras with higher performance and speed.



➔ Robonaut (L) and human-gloved hands (R)

- Highly sophisticated robots use many types of sensors to perform precision work on assembly lines, such as painting & welding.



# Image Sources

Page 1a: photo of eyes; U.S. Department of Veteran Affairs

[http://www.lexington.va.gov/features/May\\_is\\_Healthy\\_Vision\\_Month.asp](http://www.lexington.va.gov/features/May_is_Healthy_Vision_Month.asp)

Page 1b: photo of ear; State of Ohio <http://www.tclw.das.ohio.gov/Default.aspx?tabid=325>

Page 1c: photo of girl-bad smell; City of Mesa, AZ <http://www.mesaaz.gov/energy/ngsmell.aspx>

Page 5: Nerves in human hand; [www.ptwellness.org](http://www.ptwellness.org)

Page 7: Human nervous system diagram; [http://www.infovisual.info/03/038\\_en.html](http://www.infovisual.info/03/038_en.html)

Page 8: Pathway from eye to visual cortex;

[http://thebrain.mcgill.ca/flash/d/d\\_02/d\\_02\\_cr/d\\_02\\_cr\\_vis/d\\_02\\_cr\\_vis.html](http://thebrain.mcgill.ca/flash/d/d_02/d_02_cr/d_02_cr_vis/d_02_cr_vis.html)

Page 9: Human eye diagram; <http://www.ratbehavior.org/Eyes.htm>

Pages 10 and 11: Human ear anatomy; Dan Pickard, Wikimedia Commons

[www.commons.wikimedia.org](http://www.commons.wikimedia.org)

Page 12a: dog photo; Microsoft clipart <http://office.microsoft.com/en-us/images/>

Page 12b: Human nose anatomy; [www.commons.wikimedia.org](http://www.commons.wikimedia.org)

Page 13: Taste buds on human tongue; <http://commons.wikimedia.org/wiki/>

Pages 14-17: LEGO® parts and sensors; [www.LEGO.com](http://www.LEGO.com)

Page 19a&b: gloved hands and robot arms; NASA

[http://www.nasa.gov/mission\\_pages/station/main/robo-glove.html](http://www.nasa.gov/mission_pages/station/main/robo-glove.html)

Page 19c: assembly line robots; NASA [http://my.nasa.nasa.gov/worldbook/wbkids/k\\_robot.html](http://my.nasa.nasa.gov/worldbook/wbkids/k_robot.html)